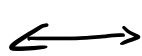


$$a \frac{\partial^2 u}{\partial x^2} + b \frac{\partial^2 u}{\partial x \partial y} + c \frac{\partial^2 u}{\partial y^2} + d \frac{\partial u}{\partial x} + e \frac{\partial u}{\partial y} + f u = g(x, y)$$

$$\Delta = b^2 - 4ac$$

$$- \Delta > 0$$

$$b^2 > 4ac$$



IPERBOLICA



2 radici reali



EQ. ONDE



$$- \Delta = 0$$

$$b^2 = 4ac$$



PARABOLICA



1

"

"

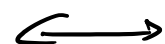


EQ. CALORE

$$\frac{\partial u}{\partial t} = a \frac{\partial^2 u}{\partial x^2}$$

$$- \Delta < 0$$

$$b^2 < 4ac$$



ELLITICA



0

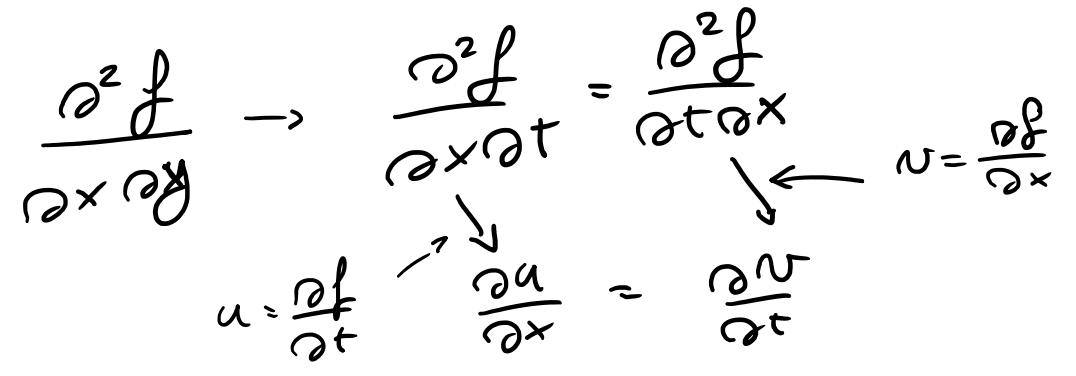
"

"

$$\frac{\partial^2 f}{\partial t^2} - c^2 \frac{\partial^2 f}{\partial x^2} = \phi$$

$$u = \frac{\partial f}{\partial t} + c$$

$$v = \frac{\partial f}{\partial t} - c$$



$$\left\{ \begin{aligned} \frac{\partial u}{\partial t} - c^2 \frac{\partial v}{\partial x} &= \phi \\ \frac{\partial v}{\partial t} - c^2 \frac{\partial u}{\partial x} &= \phi \end{aligned} \right.$$

$$\underline{U}_t + \underline{A} \underline{U}_x = \underline{\phi}$$

AUTOVAL

$$\bullet \det(\underline{\underline{A}}^T - \alpha \underline{\underline{I}}) = 0$$

$$\det \begin{bmatrix} -\alpha & -1 \\ -c^2 & -\alpha \end{bmatrix} = 0 \rightarrow \alpha^2 - c^2 = 0 \rightarrow \underline{\underline{\alpha = \pm c}}$$

AUTOVETTOR

$$\bullet (\underline{\underline{A}}^T - \alpha \underline{\underline{I}}) \underline{\underline{l}} = 0$$

$$\begin{bmatrix} -\alpha & -1 \\ -c^2 & -\alpha \end{bmatrix} \begin{bmatrix} l_1 \\ l_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$l_1 = 1$

$$\bullet \alpha = c \rightarrow -c l_1 - l_2 = 0 \rightarrow l_2 = -c$$

$$\bullet \alpha = -c \rightarrow l_2 = c$$

Moltiplicando per le equazioni precedenti:

$$1. \left(\frac{\partial u}{\partial t} - c^2 \frac{\partial v}{\partial x} = 0 \right) - c \cdot \left(\frac{\partial v}{\partial t} - \frac{\partial u}{\partial x} = 0 \right) \quad (*)$$

$$c = \frac{\partial x}{\partial t} \quad \frac{\partial u}{\partial t} - c \frac{\partial v}{\partial x} = 0 \quad (*)$$

$$-c = \frac{\partial x}{\partial t}$$

$$\frac{\partial u}{\partial t} + c \frac{\partial v}{\partial x} = 0$$

$$\frac{\partial u}{\partial t} - c \frac{\partial v}{\partial t} = \phi$$

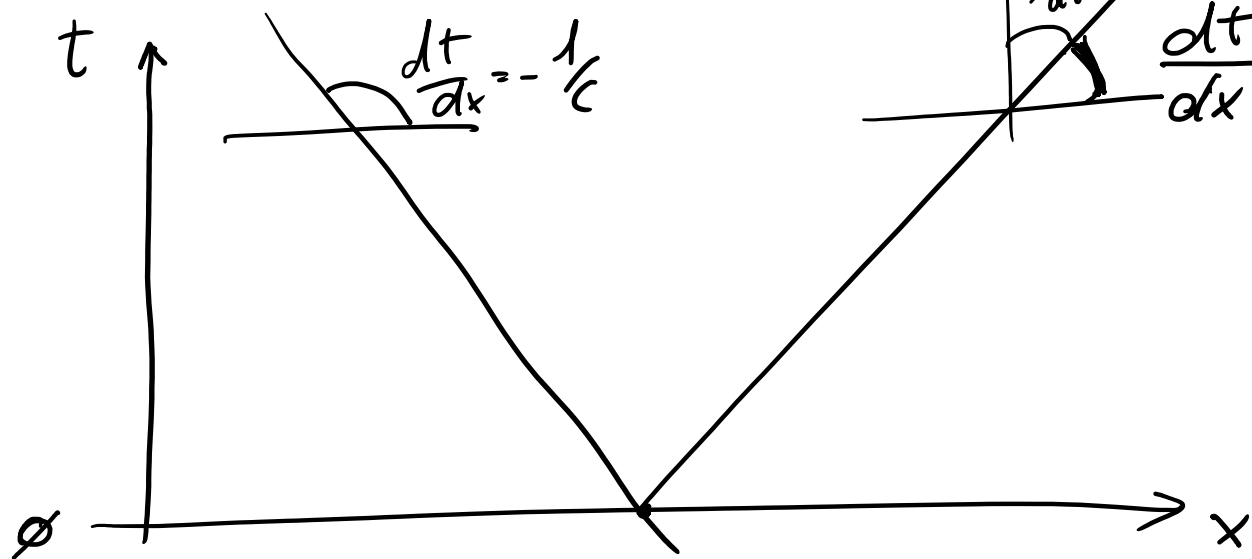
$$\text{su} \quad \frac{dx}{dt} = c$$

$$\frac{\partial u}{\partial t} + c \frac{\partial v}{\partial t} = \phi$$

$$\text{su} \quad \frac{dx}{dt} = -c$$

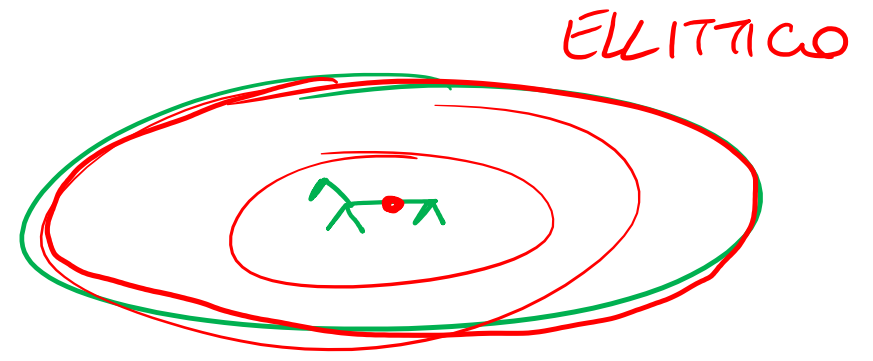
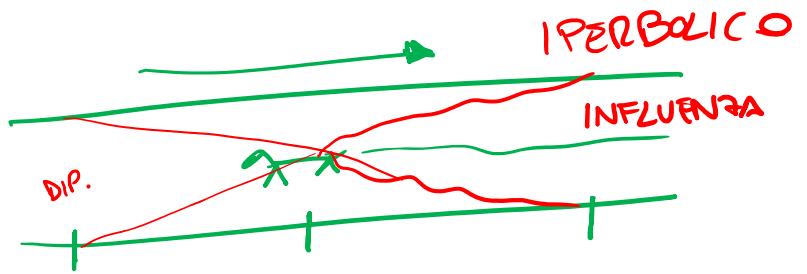
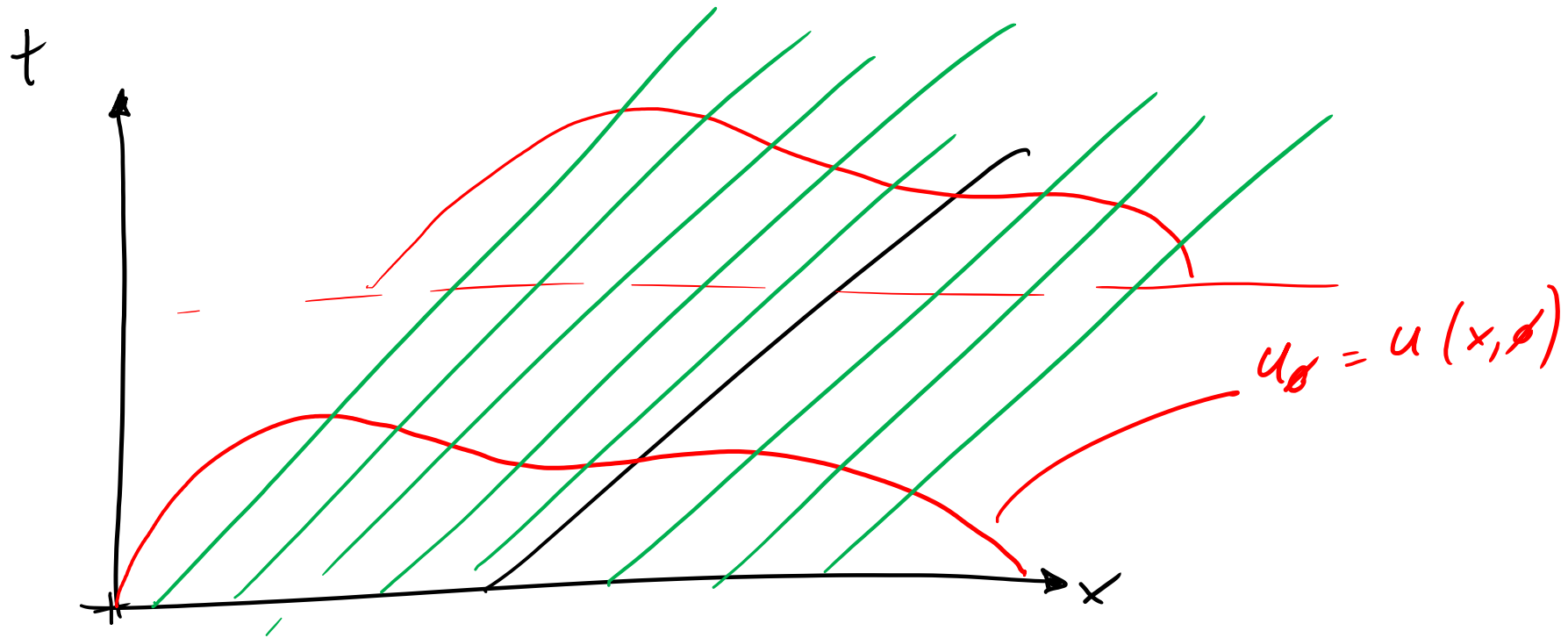
$$\frac{\partial u}{\partial t} - c \frac{\partial u}{\partial x} = \phi \quad \leftrightarrow \quad du(x, \tau) = \frac{du}{dx} \left(\frac{dx}{dt} \right) + \frac{du}{dt}$$

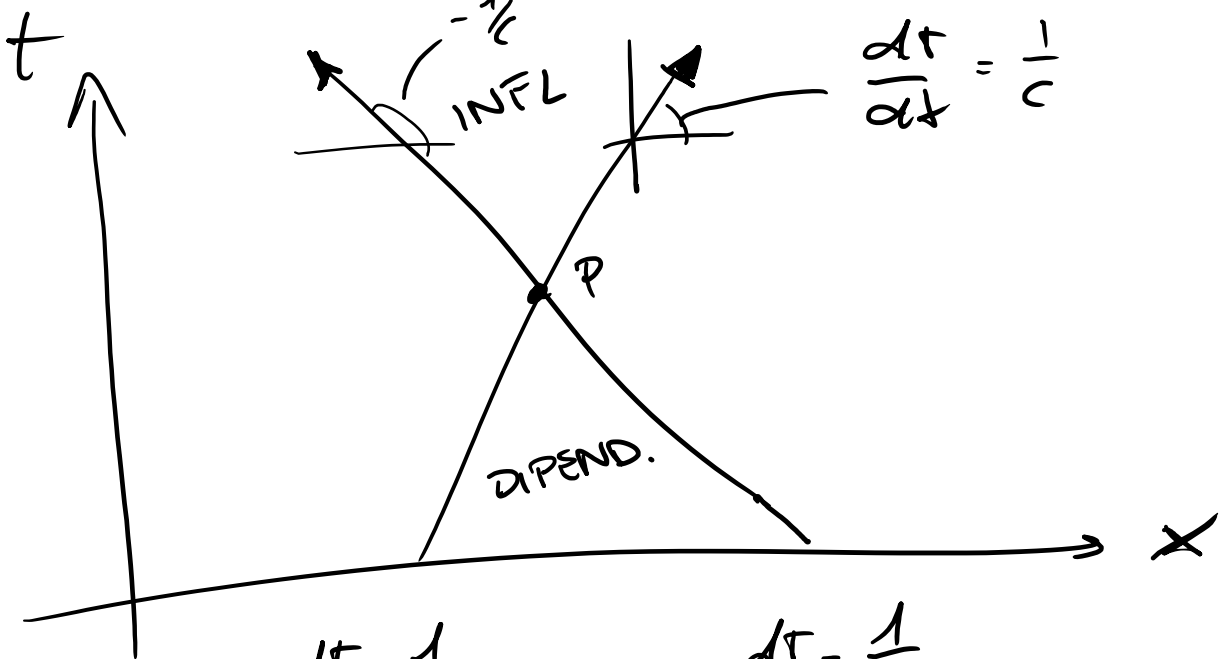
$$\frac{dx}{dt} = -c \quad (+c)$$



$$u(x, 0) = u_0$$

Metodo delle caratteristiche





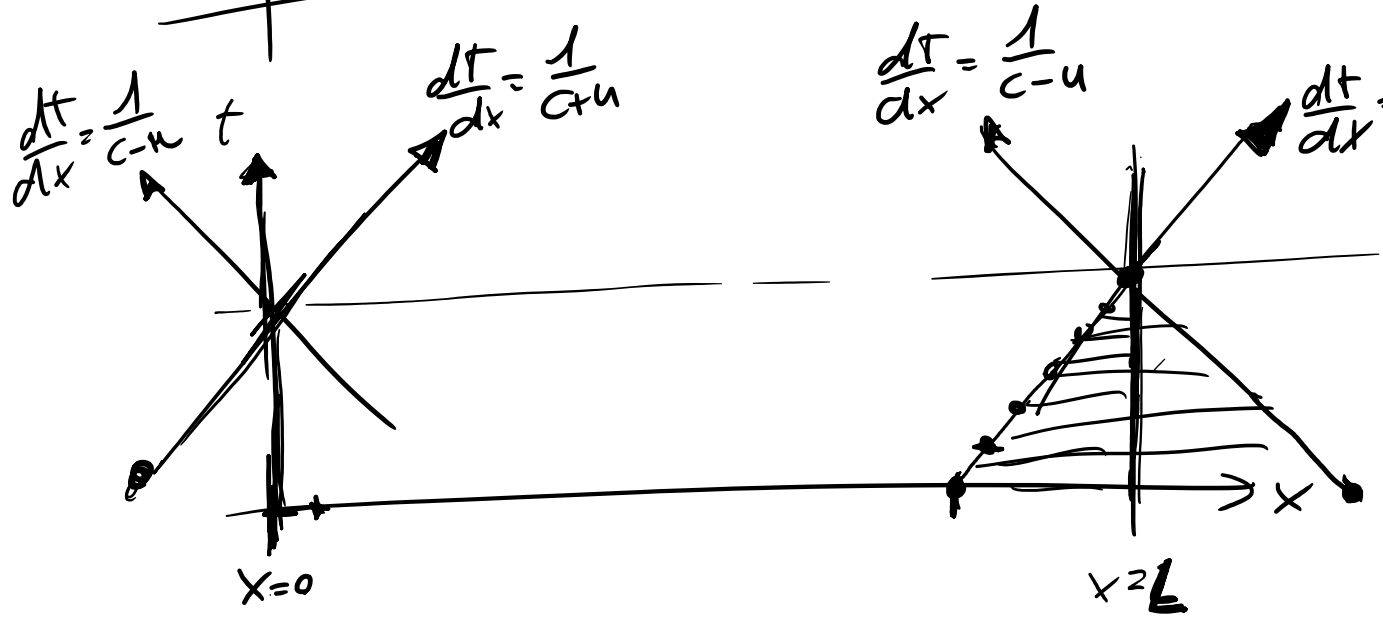
$c = \text{Speed of sound}$

$$\frac{1}{c}$$

$$\frac{1}{c-u}$$

$$-\frac{1}{c}$$

$$\frac{1}{c+u}$$



$x \in (0, L)$

$$\left. \begin{array}{l} c+u > 0 \\ c-u < 0 \end{array} \right\}$$

