### **Introduction to Machine Learning**

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#### **ML Definitions**

- Definition 1:
  - Learning is constructing or modifying representations of what is being experienced [Michalski 1986], pag. 10
- Definition 2:
  - Learning denotes changes in the system that are adaptive in the sense that they enable the system to do the same task or tasks drawn from the same population more efficiently and more effectively the next time [Simon 1984], pag. 28

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# **ML Applications**

- A) Knowledge extraction
  - To be employed in knowledge-based systems (e.g. in classification systems)
  - To be presented to humans (e.g. for scientific purposes, i.e., discovery of new scientific theories)
- B) Improvement of the performances of a machine
  - E.g. improvement of the motion and sensing capabilities of a robot

# **ML Techniques**

- Symbolic techniques (applications A and B)
  - Representation languages
    - Propositional
    - First order
- Statistical techniques (applications A and B)
  - Representation language
    - Propositional
    - First order
- Neural networks (application B)

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#### **Inductive Learning**

- The system starts from observations provided by a teacher or from the environment
- It generalizes them, i.e. it obtains knowledge hopefully valid also in cases not yet observed (induction)
- · Two types of inductive learning:
  - Learning from examples: the observations are grouped into a set of positive examples, instances of the concept to be learned, and into a set of negative examples, non-instances of the concept
  - Descriptive learning: the aim is to find regularities in the data

#### **Inductive Learning from Examples**

- Universe U: set U of all the objects (also called instances) of the domain
- Concept C: subset of U, C⊆U
- Also called class
- Object description language  $L_{\text{o}}$
- Concept description language L<sub>c</sub>
- A procedure for verifying whether a description D<sub>C</sub> of a concept C is satisfied by a description D<sub>x</sub> of an object x, meaning that x∈C

# **Inductive Learning from Examples**

- · Informally:
  - Learning a concept C means finding a description  $D_C$  of C such that, for all objects  $x \in U$ ,  $x \in C$  iff  $D_x$  satisfies  $D_C$ .

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# **Inductive Learning from Examples**

- · Fact: description of an object
- Example for a concept C: labeled fact,
  - + label if the object belongs to the concept (positive example)
  - - label if the object does not belong to the concept (negative example)
- Training set E: set of labeled facts, subsets:
  - E+: set of positive examples
  - E: set of negative examples
- Two classes: + and -, in general we may have more than two classes

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# **Inductive Learning from Examples**

- Hypothesis: description of the concept to be learned
- If a fact satisfies a hypothesis we say that the hypothesis covers the fact
- · Coverage test function

covers(H,e)

- returns true if e is covered by H and false otherwise
- Extension to set of examples:  $covers(H,E) {=} \{e \in E | covers(H,e) {=} \ true\}$

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# **Inductive Learning from Examples**

We want to find an hypothesis H such that

 $\forall e \in U$ : covers(H,e) $\Leftrightarrow$ e  $\in$  C

• In practice, we know only instances from E

So we require that

 $\forall e \in E$ : covers(H,e) $\Leftrightarrow$ e  $\in$  C

• Thus

 $- \ covers(H,e) {\Rightarrow} \ e \in C$ 

 $- \neg \ covers(H,e) {\Rightarrow} \neg \ (e \in C)$ 

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#### **Inductive Learning from Examples**

- Given a set E of positive and negative examples of a concept C, expressed in object description language
- Find an hypothesis H, expressed in a concept description language  $L_{\rm c}$ , such that
  - Every positive example  $e^+ \in E^+$  is covered by H
  - No negative example  $e^- \in E^-$  is covered by H

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#### **Completeness and Consistency**

 An hypothesis H is called complete if it covers all the positive examples, i.e.

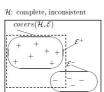
 $covers(H,E^+)=E^+$ 

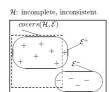
• An hypothesis H is called consistent if it does not cover any negative examples, i.e.

 $covers(H,E^-)=\emptyset$ 









H: incomplete, consistent

 $covers(\mathcal{H}, \mathcal{E})$ 

# **Representation Languages**

- · Propositional or attribute-value languages
- · Frame-based languages
- · First order, logic or relational languages

#### **Attribute-value languages**

- Every instance is described by the values taken by a set of attributes (fixed for all the instaces)
- The training set can be represented as a table
- · Attributes can be
  - Boolean or binary (2 values)
  - Discrete or nominal (more than 2 values)
  - Ordinal (ordered discrete values)
  - Continuous or numeric (interval or ratio scale, integer or real)
- If there are k attributes, each instances can be described by a point in a k-dimensional space

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# **Example**

- · Universe: set of athletes
- · Instances described by
  - height=continuous (real)
  - weight=continuous (integer),
  - preferred\_music=discrete, values={rock,pop,rap}
- Example of instance height=1.85m, weight=90kg, preferred\_music=rock
- Class=sport played, values={football, baseball, basketball, boxing}

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#### **Attribute-Value Concept Description** Languages

- Single production rule, conjunction in the body, class in the head
- · Example: football player
  - If weight<100 and preferred\_music=rock → football</li>
- They can also be represented as a tuple with a constraint for every attribute (class is left implicit):
  - attribute=?, all the values satisfy the constraint
  - attribute=value
  - attribute<value
  - attribute=Ø, no value is acceptable (the hypothesis covers 0
- · Example: football player
  - <height=?,weight<100, preferred\_music=rock>

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#### **Attribute-Value Concept Description** Languages

- Set of production rules, any Boolean formula in the body, class in the head
- · Often only conjunctions in the body
- · Often decision lists:
  - The rules are tried in order
  - The first that fires gives the class
- · Example: baseball player weight<100 and preferred\_music=pop  $\rightarrow$  baseball weight<100 and preferred\_music=rap  $\rightarrow$  basketball

## Attribute-Value Concept Description Languages

- · Decision trees:
  - Every node corresponds to a test on an attribute
  - Every child corresponds to a result of the test
  - Every leaf is associated to a class

Example

Weight<100

yes

no

preferred\_music=?

rock

rap

pop

football

basketball

baseball

boxing

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# **Attribute-Value Languages**

- Equivalent to propositional logic:
  - Each equality or disequality can be seen as a proposition (zero arity predicate) that is either true or false for an instance
  - There are no variables, quantifiers and predicates with arity > 0

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# Attribute-Value Concept Description Languages

- · Bayesian networks
  - Represent probabilistic dependencies among attributes
  - Qualitative component: the parents of a node are the attributes that directly influence the node
  - Quantitative component: strength of the dependency

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#### **Problems of Propositional Languages**

- Instances with parts, subparts, attributes of subparts and relation among subparts
- Example: jones family, components name: dave, son: mike, father: ron, age: 70, hair: white name: mike, son: junior, father: dave, age: 35 name: junior, father: mike, age: 3
- In general, families may have a variable number of components and each component may have a variable number of attributes

# **First-Order Languages**

- Instances described by logic theories
- They allow to represents easily parts of objects, attributes of parts and relations among parts
- · Example:
  - Parts: "object"(object\_id, part\_id)
  - Attributes of parts: "attribute" (part\_id,value)

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#### **Example**

• Instance: jones family, first-order representation:

family(jones,dave).

family(jones,mike).

family(jones,junior).

age(dave,70).

hair(dave,white).

age(mike,35). age(junior,3).

father(dave,mike).

father(mike,junior).

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# **Example: Blocks World**

•Instance:



• Instance e: first-order representation object(e,a). object(e,b), square(a). triangle(b). large(a). small(b). on-table(a). on(b,a).

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# First-Order Languages Concept Description Languages

- They allow to use variables and quantifiers
  - Example: family with a grandfather gf(X):-family(X,Y),father(Y,Z),father(Z,W). gf(X):-family(X,Y),father(Y,Z),mother(Z,W).
- They allow to represent recursive concepts
  - Example: ancestor ancestor(X,Y):-father(X,Z),ancestor(Z,Y).

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#### **First-Order Languages**

- Advantages:
  - Uniform representation of instances and hypothesis
  - The semantics of these languages is well defined and amply studied
  - Availability of well-engineered interpreters

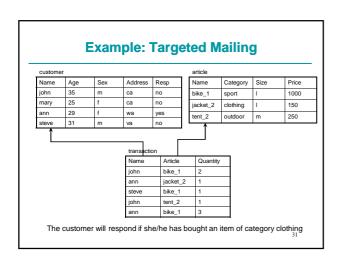
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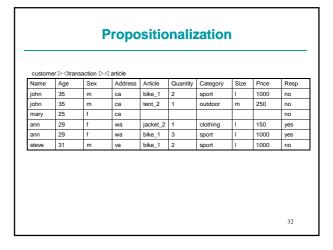
#### **Example: Targeted Mailing**

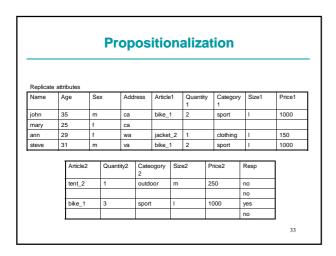
customer

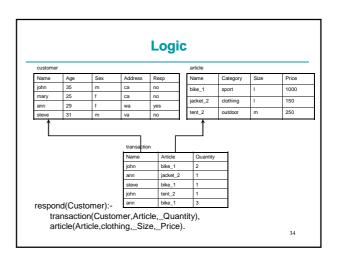
Name	Age	Sex	Address	Resp
john	35	m	ca	no
mary	25	f	ca	yes
ann	29	f	wa	no
steve	31	m	va	no

If Age<30 and Address=ca then Resp=yes









# **Machine Learning Techniques**

- Attribute-value languages:
  - Version spaces
  - Decision trees
  - Production rules
  - Instance based methods
  - Bayesian networks
- · First-order languages:
  - Inductive Logic Programming
  - Statistical Relational Learning

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# **Machine Learning**

- Usually Machine Learning algorithms perform a search in the space of the concept description language
- The aim is to find the hypothesis that best matches the training set
- Often the search space is a subset of all the hypotheses in the language (language bias)

#### **Evaluation Measures**

· Confusion matrix: predictions of a hypothesis on a set of

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pos	neg	<-Predicted class		
TP	FN	pos		
FP	TN	neg		

- TP=true positive, FN=false negative, FP=false positive, TN=true negative, P=TP+FN=positive, N=FP+TN=negative

  Accuracy=(TP+TN)/(TP+TN+FN+FP)
- Error rate=(FP+FN)/(TP+TN+FN+FP)=1-Accuracy
- TP Rate=TP/(TP+FN)=TP/P
- FP Rate=FP/(FP+TN)=FP/N
- Precision=TP/(TP+FP)
- Recall=TP/(TP+FN)=TP Rate
- **F-meaure**=2\*Precision\*Recall/(Precision+Recall)

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[Michalski 1986] Michalski, R. S. "Understanding the nature of learning: Issues and research directions" in Michalski, R. S., Carbonell, J. G., and Mitchell, T. M., editors, Machine Learning - An Artificial Intelligence Approach, Volume II, Morgan Kaufmann Publishers, Los Altos, California, pages 3—26, 1986.

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[Simon 1984] Simon, H. A. "Why should machines learn" In Michalski, R. S., Carbonell, J. G., and Mitchell, T. M., editors, Machine Learning - An Artificial Intelligence Approach, Springer-Verlag, Berlin, pages 25—37, 1984.